



Towards a global optimisation of the tracker layout: new tools and ideas

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Why a new tracker optimisation?

- What drives the optimal tracker geometry and size?
 - acceptance (driven by physics: lifetime, rapidity & momentum spectra)
 - running conditions (luminosity \rightarrow pile-up \rightarrow occupancies)
 - performance (detector technologies)
 - cost

 \Rightarrow is the original 9m-long tracker still optimal for $\mathscr{L} = 1.5 \times 10^{34} \,\mathrm{cm}^{-2} \,\mathrm{s}^{-1}$?

- High luminosity
 - strips don't scale well with luminosity (\Rightarrow need for inner tracker)
 - pixels are more "natural" candidates
- Magnet
 - can the LHCb magnet be operated until ≥ 2040 ? (structural integrity, cost of electricity)
 - if replaced, is a new superconducting magnet an option?

\Rightarrow LHCb could consider a reoptimisation of the tracker/detector

Path to re-optimisation

- Define the target tracker characteristics:
 - fully pixel tracker
 - smaller tracker dimensions (factor 3 in this study)
 - new superconducting magnet $([\vec{B} \cdot d\vec{\ell}] = 4 \text{ Tm})$
 - remove RICH1 to minimise material budget
 (⇒ PID optimisation will be needed: RICH/CALO/MUON)
- Tool development:
 - use momentum resolution, dp/p, as figure of merit
 - not studied here: efficiency, ghosts, occupancy (and impact on PID detectors)
 - flexible standalone code to evaluate dp/p for various geometries
 - developed and implemented by Renato Quagliani
 - based on the "Weight matrix formalism" proposed by Pierre Billoir at the <u>6th LHCb computing workshop, 2015</u>
- Toy studies:
 - $1.\,\mathrm{Run}\ 3$ geometries, for validation of the tools
 - $2.\,\mathrm{Run}$ 5 (FTDR, and variations), to define the benchmark
 - 3. Run 5 (MiniLHCb)

 \rightarrow MiniL

Method and basic principle

- <u>Weight matrix formalism</u> (by Pierre Billoir)
- Add multiple scattering as noise around unaffected reference trajectory
- Build the Kalman Filter to obtain the sensitivity on the fitted parameters for each measurement, given the previous measurements
 - 1. Use barycenter with matrices $(W = C^{-1})$ as measurement weights
 - 2. Propagation along z induces "rotation-elongation" of the ellipse
 - 3. New measurement of weight W_{meas} is added to the propagated state
 - 4. Noise from multiple scattering added to W⁻¹ at boundaries of material layers
 - 5. Invert W after the last measurement to obtain the expected σ_p



Full details in <u>talk by Renato Quagliani</u>, "Upgrade2 studies, Mini LHCb" at <u>RTA WP6 meeting</u>, 23 March 2023

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Layer description

The Weight method

Ingredient 1: a measurement is added at given z (+ W_{meas})

A measurement at a given z is introduced with flexible information on $z,\sigma,\alpha,thick$

What is the contribution to the fit assuming no misalignment and track pass exactly

- Where σ is derived from the pitch size of the measurements (Run3 detectors):
 - **1** Velo : $\sigma = \frac{56 \, \mu m}{\sqrt{12}} = 16 \, \mu m$ 2 UT : $\sigma = \frac{196 \,\mu\text{m}}{\sqrt{12}} = 56 \,\mu\text{m}$, corrected for $|x, y| < 200 \,\text{mm}$ to be $\frac{96}{\sqrt{12}} \,\mu m$ 3 SciFi : $\sigma = \frac{250 \,\mu\text{m}}{\sqrt{12}} = 80 \,\mu\text{m}$ (rounded to 100 μm as baseline)¹
- Where α is a stereo angle:
 - **1** Pixel-like: duplicate contribution with $\alpha = 0(90)$ at same z 2 x-u-v-x measurements : $\alpha = 0/+5^{\circ}/-5^{\circ}/0$ (SciFi & UT)
- *thick* is δ_z/X_0 of the measurement layer. Noise for measurements made dimensionless (thin-layer approximation).

¹No dependency on track slope and 1.2mm thickness of SciFi so far in toy-model, only rough assumption.

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Momentum Resolution studies with toy model for Upgrade2 and Run3 scenarios March 27, 2023

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cf. talk by Renato Quagliani, "Upgrade2 studies, Mini LHCb"

at RTA WP6 meeting, 23 March 2023

Detector geometries and magnetic field



- GDML file loaded for material budget navigation¹
 - removed RICH1 and replaced with air
- Magnetic field:
 - default LHCb field map
 - parabolic extrapolator to propagate the tracks in the field
 - emulated miniLHCb magnet by increasing the field and shorten the lever arm by the same factor (=3 in this study)

Examples of simulated geometries



Run5 (UT4Pix, Pix/SciFi mix)



Run5 (UT4Pix, Pix)



MiniLHCb (UT4Pix950, Pix)



MiniLHCb (UT4Pix1300, Pix)



MiniLHCb (UT4Pix800, Pix)



Sample of tracks

- Generate xgen file of $B^\pm \to K^\pm \mu^+ \mu^-$ decays
- Use the K^{\pm} kinematics for the study (10k events)
- Emulate K_S^0 by linear extrapolation of K^{\pm} from origin to fixed z_{decay} , then start propagation with charge from z_{decay}



LONG TRACKS

Run 3 resolution (for tool validation)

- Predicted resolution in Run 3, compared with HLT2 Kalman fit
 - results are in agreement with the expectation
 - dependence on η not perfectly reproduced



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From Run 3 to Run 5

Run3 + UT pixel (3 or 4 layers, $50 \times 150 \,\mu\text{m}^2$ or $30 \times 30 \,\mu\text{m}^2$)



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From Run 3 to Run 5



MiniLHCb Tracker

- Shorter lever arm has a visible impact on momentum resolution
- Sensitivity to the location of the measurements \rightarrow impact on long-lived particles
- Performance can be better than FTDR at low p, worse at high p



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DOWNSTREAM+T TRACKS

Long-lived particles in Run3

- Emulating $K_{\rm S}^0$ with K^+ track
- Top: have measurement in UT, decay before magnet region
- Bottom: no measurement in UT, decay in magnet region



DOWNSTREAM+T TRACKS

Long-lived particles: from Run3 to Run5

- Changing SciFi for SciFi/Pix or full-Pix, and changing UT
- Top: no VELO measurements, only UT+Downstream \rightarrow major improvement from pixels for z < 2.4 m
- Bottom: pixels are powerful in fringe field tails



DOWNSTREAM+T TRACKS

Long-lived particles: miniLHCb

- With MiniLHCb, 1% 10% resolution up to $z_{decay} = 2.3 \text{ m}$
- Clear acceptance effect, can be partly recovered from UT and downstream stations in the B field tail
- Long-lived particles are neutral \rightarrow maybe gain in acceptance at low p



Track distribution in CALO region

- Consider a $8m\times8m$ detector at 10 (13) meters
- Kaons with $p>2.5\,{\rm GeV}$ from $B\to K\mu\mu$ are in acceptance
 - $97.5\,(93.4)\,\%$ of the time in the nominal magnetic field
 - 95 (90) % of the time in the $B \times 3$ setup (MiniLHCb)



Summary

- Momentum resolution improves from using
 - fully pixel tracker (resolution)
 - lower material budget (multiple scattering)
 - placing tracking stations in the tail of the \overrightarrow{B} field
- The MiniLHCb setup looks interesting:
 - full downstream pixel detector with $9\times {\rm smaller}$ area
 - lower material budget (UT, no RICH1, less air), i.e. fewer secondaries
 - \overrightarrow{B} field map and detector size/geometry can be further tuned for performance
 - some impact on long-lived physics programme, but room for improvement
- Global optimisation:
 - must include RICH, CALO, MUON (and VELO?)
 - can include beam pipe design to minimise secondaries
 - resolution, occupancy, efficiency, ghosts, \ldots

Conclusion

- A small-size tracker can provide FTDR-like momentum resolution
- Global reoptimisation of the detector geometry/technology may provide a descoping option with reduced loss of physics reach
- A tool is available for studying the momentum resolution for various geometries; can be extended to study IP resolution, impact of misalignments



Backup

VELO model

The detection layers used

 Different layers of material used, with a 'thin' thickness scatter model and a resolution in the reference plane (prior to stereo rotation)

Velo measurements

						Velo mo	dules (2)							
Velo modules (1)				<i>z</i> [mm]	α	σ[μm]	$\delta_z / X_0 [\%]$	geometry						
<i>z</i> [mm]	α	σ[μm]	$\delta_z / X_0 [\%]$	geometry	50	0	15.9	0.61	velo					
-275	0	15.9	0.61	velo	50	90	15.9	0.61	velo			Velo mod	dules (3)	
-275	90	15.9	0.61	velo	75	0	15.9	0.61	velo	<i>z</i> [mm]	α	σ [μm]	δ_z/X_0 [%]	geometry
-250	0	15.9	0.61	velo	75	90	15.9	0.61	velo	325	0	15.9	0.61	velo
-250	90	15.9	0.61	velo	100	0	15.9	0.61	velo	325	90	15.9	0.61	velo
-225	0	15.9	0.61	velo	100	90	15.9	0.61	velo	400	0	15.9	0.61	velo
-225	90	15.9	0.61	velo	125	0	15.9	0.61	velo	400	90	15.9	0.61	velo
-200	0	15.9	0.61	velo	125	90	15.9	0.61	velo	500	0	15.9	0.61	velo
-200	90	15.9	0.61	velo	150	0	15.9	0.61	velo	500	90	15.9	0.61	velo
-125	0	15.9	0.61	velo	150	90	15.9	0.61	velo	600	0	15.9	0.61	velo
-125	90	15.9	0.61	velo	175	0	15.9	0.61	velo	600	90	15.9	0.61	velo
-50	0	15.9	0.61	velo	175	90	15.9	0.61	velo	650	0	15.9	0.61	velo
-50	90	15.9	0.61	velo	200	0	15.9	0.61	velo	650	90	15.9	0.61	velo
-25	0	15.9	0.61	velo	200	90	15.9	0.61	velo	700	0	15.9	0.61	velo
-25	90	15.9	0.61	velo	225	0	15.9	0.61	velo	700	90	15.9	0.61	velo
0	0	15.9	0.61	velo	225	90	15.9	0.61	velo	750	0	15.9	0.61	velo
0	90	15.9	0.61	velo	250	0	15.9	0.61	velo	750	90	15.9	0.61	velo
25	0	15.9	0.61	velo	250	90	15.9	0.61	velo					
25	90	15.9	0.61	velo	275	0	15.9	0.61	velo					
					275	90	15.9	0.61	velo					

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VELO description identical in all geometries

T models

The detection layers used

- Different layers of material used, with a 'thin' thickness scatter model. Duplicate at z to add both x/y resolution.
- For stronger B field, alternative locations in z
- Tested also $30 \times 30 \,\mu m^2$ pitch size case.
- UTRun3 material reduced per layer from 2% to 1% in UT3/4Pix.
 T measurements Run5 (3 layers)
 UT4Pix

UT measurements Run3

UTRun3								
<i>z</i> [mm]	α	σ[μm]	$\delta_z / X_0 [\%]$	geometry				
2327.5	0	55	2	UTa				
2372.5	5	55	2	UTa				
2597.5	-5	55	2	UTb				
2642.5	0	55	2	UTb				

	UT3Pix									
	<i>z</i> [mm]	α	σ[μm]	$\delta_z / X_0 [\%]$	geometry					
	2327.5	0	15	0.5	UTa					
	2327.5	90	43	0.5	UTa					
	2485.5	0	15	0.5	UTb					
	2485.5	90	43	0.5	UTb					
1	2642.5	0	15	0.5	UTb					
	2642.5	90	43	0.5	UTb					

		U I 4Pix									
	<i>z</i> [mm]	α	σ [μ m]	δ_z/X_0 [%]	geometry						
1	2327.5	0	15	0.5	UTa						
	2327.5	90	43	0.5	UTa						
	2432.5	0	15	0.5	UTa						
	2432.5	90	43	0.5	UTa						
	2537.5	0	15	0.5	UTb						
	2537.5	90	43	0.5	UTb						
	2642.5	0	15	0.5	UTb						
	2642.5	90	43	0.5	UTb						

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Downstream tracker models

Detector specifics (resolution/acceptance)

The detection layers used

Different layers of material used, with a 'thin' thickness scatter model and a resolution in the reference plane (prior to stereo rotation) Mighty Tracker

z [mm]

 α

-5

-5

-5

Downstream region measurements

D9	$\mathbf{Run3}$
KUII3	(100% pixe
SciFi	Pixels

		30	.11 1		Pixeis				
<i>z</i> [mm]	α	σ [μ m]	δ_z/X_0 [%]	geometry	<i>z</i> [mm]	α	σ[μm]	$\delta_z / X_0 [\%]$	geometry
7827	0	100	1.1	FullSciFi	7827	0	15	0.5	Pixels
7897	5	100	1.1	FullSciFi	7827	90	43	0.5	Pixels
7967	-5	100	1.1	FullSciFi	8037	0	15	0.5	Pixels
8037	0	100	1.1	FullSciFi	8037	90	43	0.5	Pixels
8509	0	100	1.1	FullSciFi	8509	0	15	0.5	Pixels
8579	5	100	1.1	FullSciFi	8509	90	43	0.5	Pixels
8649	-5	100	1.1	FullSciFi	8719	0	15	0.5	Pixels
8719	0	100	1.1	FullSciFi	8719	90	43	0.5	Pixels
9194	0	100	1.1	FullSciFi	9194	0	15	0.5	Pixels
9264	5	100	1.1	FullSciFi	9194	90	43	0.5	Pixels
9334	-5	100	1.1	FullSciFi	9404	0	15	0.5	Pixels
9404	0	100	1.1	FullSciFi	9404	90	43	0.5	Pixels

(U2 FTDR) Pix/SciFi mix

σ [μ m]	$\partial_z / X_0 [\%]$	geometry			D.,				
15	0.5	InnerPix			nu	G H			
43	0.5	InnerPix					1		
100	1.1	SciFiExternalOnly		miniLHCb					
100	1.1	SciFiExternalOnly					<u> </u>		
100	1.1	SciFiExternalOnly	Pix3 = Pixels at z/3 location						
15	0.5	InnerPix	<i>z</i> [mm]	α	σ [μ m]	δ_z/X_0 [%]	geometry		
43	0.5	InnerPix	2609	0	15	0.5	Pixels3		
100	1.1	SciFiExternalOnly	2609	90	43	0.5	Pixels3		
15	0.5	InnerPix	2679	0	15	0.5	Pixels3		
43	0.5	InnerPix	2679	90	43	0.5	Pixels3		
100	1.1	SciFiExternalOnly	2836	0	15	0.5	Pixels3		
100	1.1	SciFiExternalOnly	2836	90	43	0.5	Pixels3		
100	1.1	SciFiExternalOnly	2906	0	15	0.5	Pixels3		
15	0.5	InnerPix	2906	90	43	0.5	Pixels3		
43	0.5	InnerPix	3064	0	15	0.5	Pixels3		
100	1.1	SciFiExternalOnly	3064	90	43	0.5	Pixels3		
15	0.5	InnerPix	3134	0	15	0.5	Pixels3		
43	0.5	InnerPix	3134	90	43	0.5	Pixels3		
100	1.1	SciFiExternalOnly							
100	1.1	SciFiExternalOnly							
100	1.1	SciFiExternalOnly							
15	0.5	InnerPix							
43	0.5	InnerPix							
100	1.1	SciFiExternalOnly							

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