



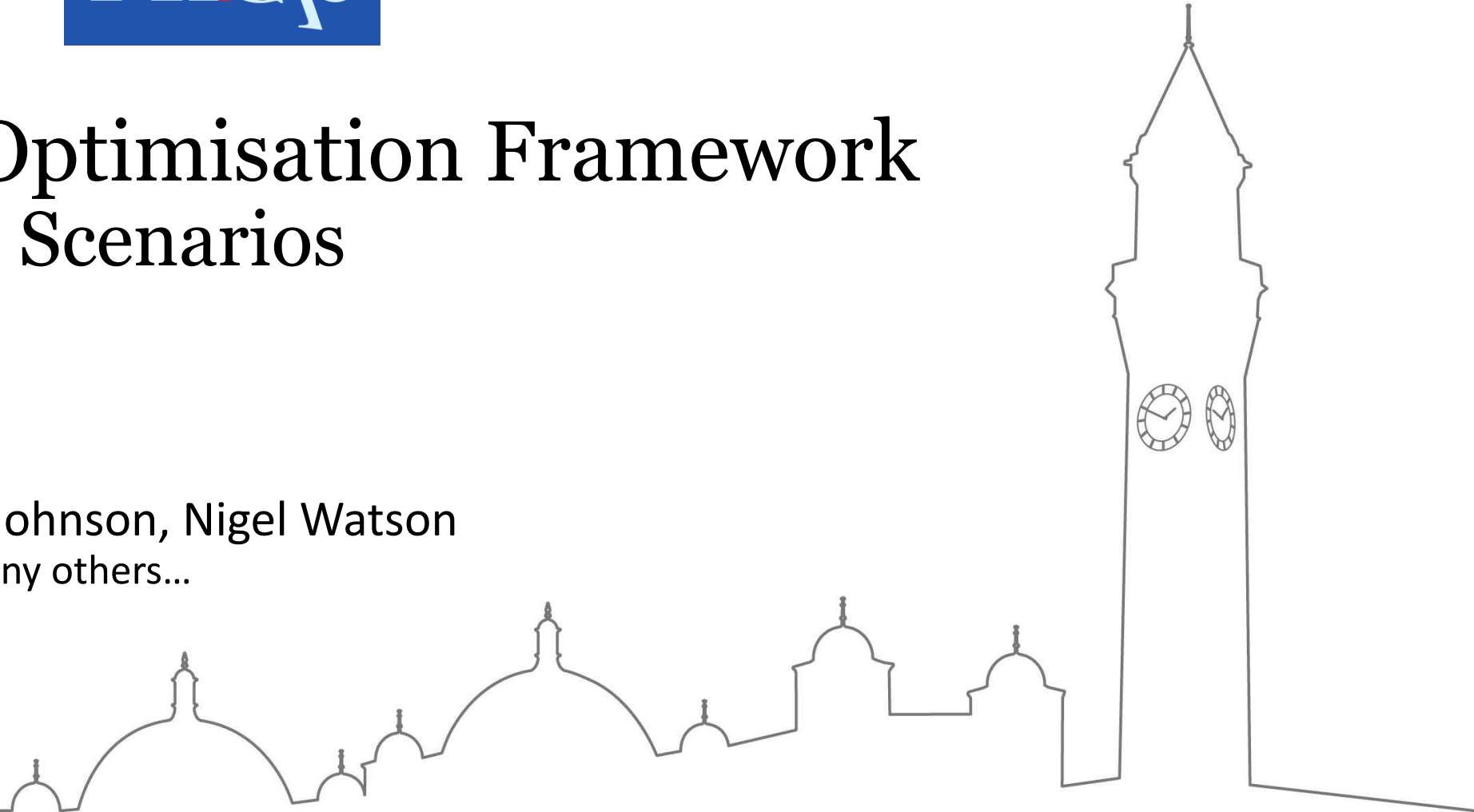
UNIVERSITY OF  
BIRMINGHAM



# UII Global Optimisation Framework Future VELO Scenarios

29/03/23

**Dan Thompson**, Dan Johnson, Nigel Watson  
+ Tim, Laurent, Kazu & many others...



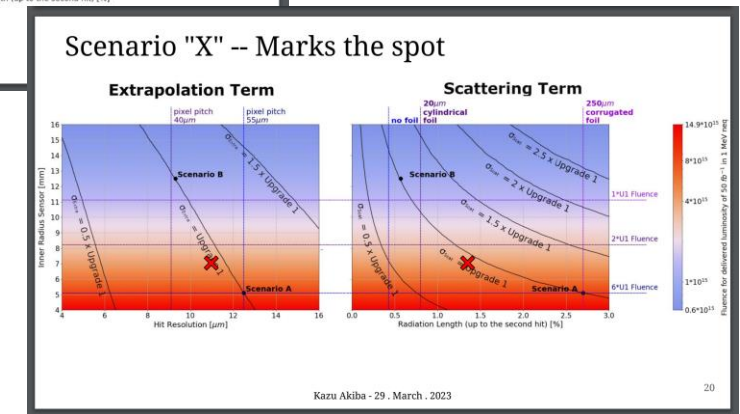
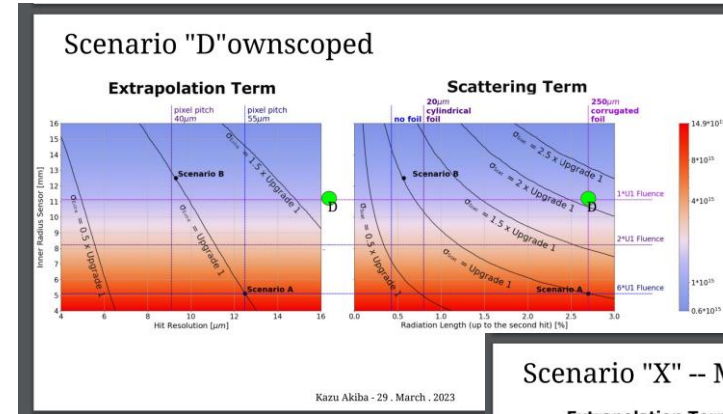
# Global Optimisation Simulation Tool

## Aims

- Create tool to **evaluate global physics performance as well as individual sub-detector metrics** after geometry changes in a quick and consistent way
- Use the latest and greatest simulation versions and detector models as baseline
- Use LHCb core software where possible (Gauss, Moore)

## This Presentation

- Developments made within the VELO UII Simulation group applying these aims to iterate on VELO designs
- Specifically **Scenario A vs B vs D(escoped)**
- How this can extend beyond the VELO

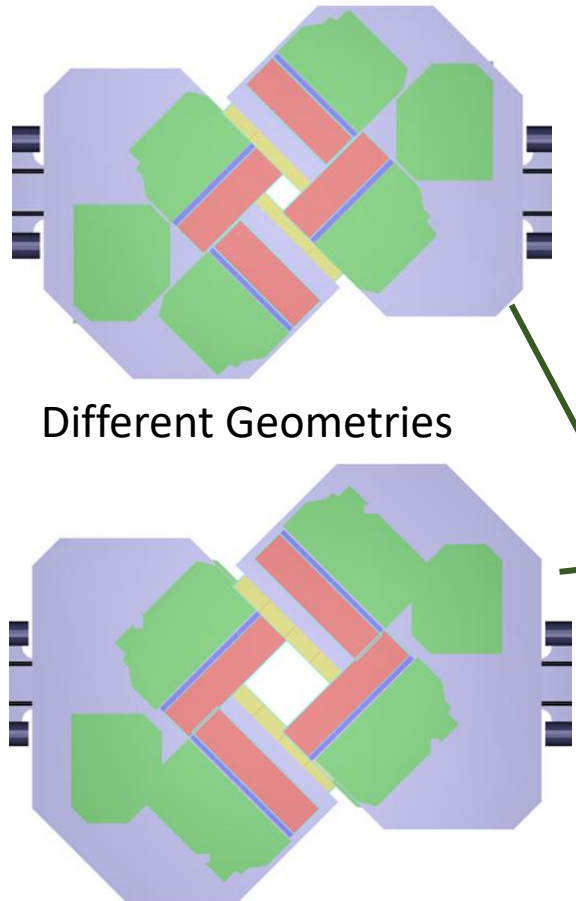


See [Kazu's talk](#) for more info on the specifications behind these scenarios...

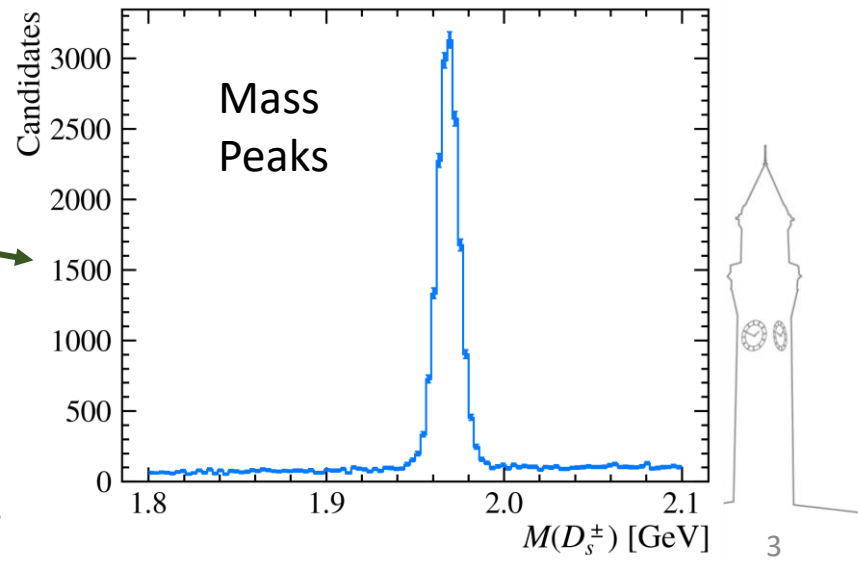
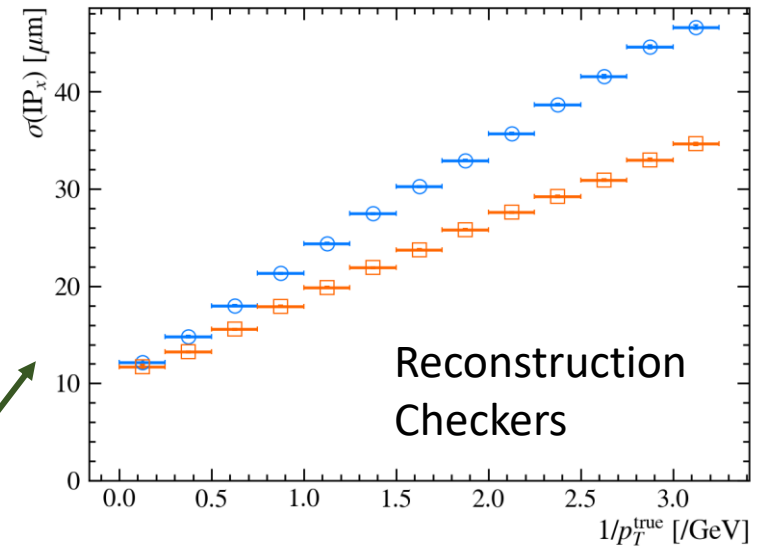
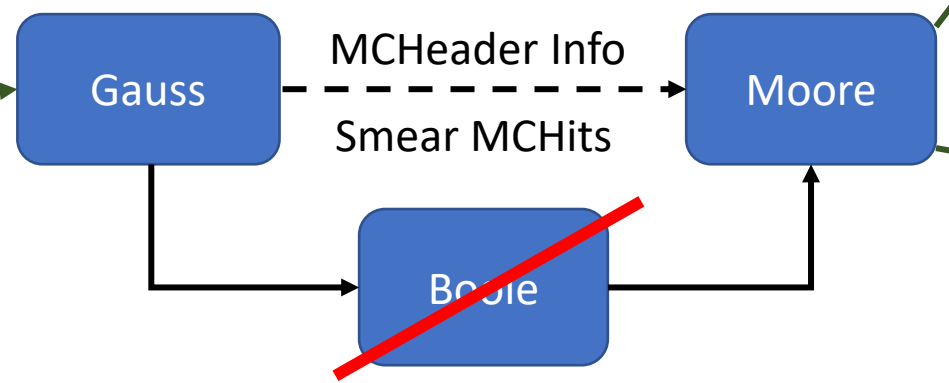
# Adaptable Simulation Chain

- Chain packaged into one [repo](#) with installation instructions
- Works with [lb-stack-setup](#)
- Custom [Gaussino](#), [LHCb](#), [Rec](#) Branches

- Gauss-on-Gaussino w/ **Sim 11 & DD4Hep**
- Boole is skipped using **“Fake Clustering”**
  - Run Moore directly on Gauss output
  - Input  $(\sigma_{xy}, \sigma_t) \rightarrow$  Smear Hits  $\rightarrow$  Fake Clusters  $\rightarrow$  Tracks
  - Fitted tracks emulated using downstream momentum parameterisation
- Output a combination of **standard reconstruction checkers** + a **“U2 Tuple”** that allows flexible analysis + **physics reconstruction** if run with specific event types.



Different Geometries



# Parameterised VELO Model

- UI Velo model adapted to allow quicker development of “Scenarios”
- **Cylindrical Foil** used (if not studying U1 geometry) to speed up iteration
- Geometry controlled by 5 main parameters:
  - **Closest Sensor to IP** (5.1 mm for UI)
  - **Pixel Pitch** (55  $\mu\text{m}$  for UI)
  - Number of ASICs
  - **Cylindrical Foil thickness** & clearance from closest sensor
- Individual rotation of station about z-axis also possible

- [Parameterised  \$S\_B\$  Detector Branch](#)

```
<!-- DEFINING PARAMETERS -->
<constant name="VP:ClosestPixel" value="12.515*mm"/>

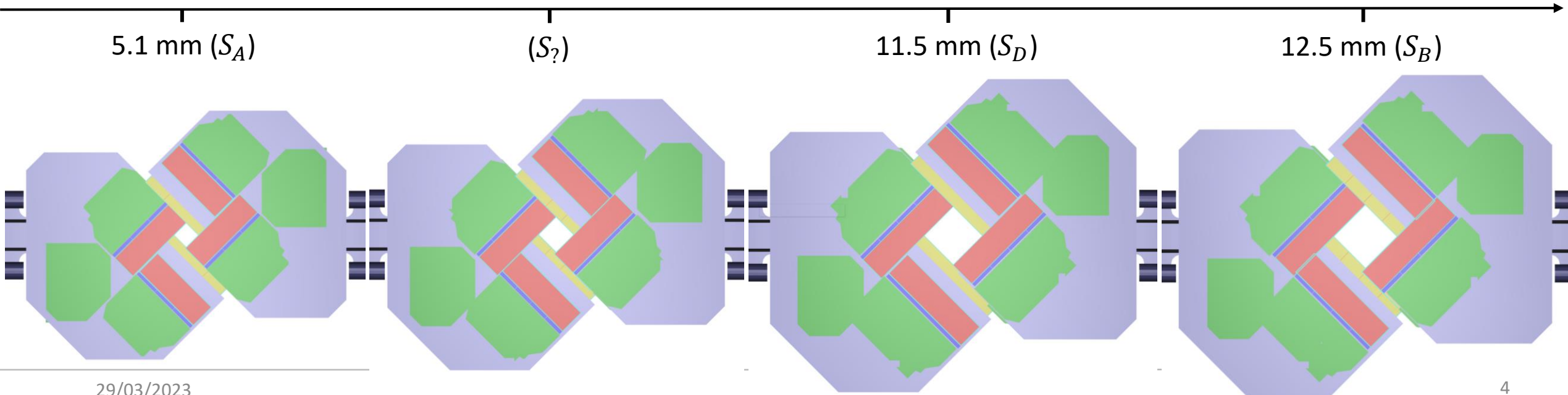
<!-- Pixel size -->
<constant name = "VP:PixelSize" value = "0.040*mm"/>

<!-- Target Number of Chips, set to 0 for auto-->
<constant name = "VP:TargetNChips" value = "0"/>

<!-- For the Cylindrical Foil, placed here for convenience -->
<constant name="VP:CylindRFoilThickness" value="0.020*mm"/>

<!-- Distance from closest pixel to foil -->
<constant name="VP:CylindRFoilClearance" value="1.5*mm"/>
```

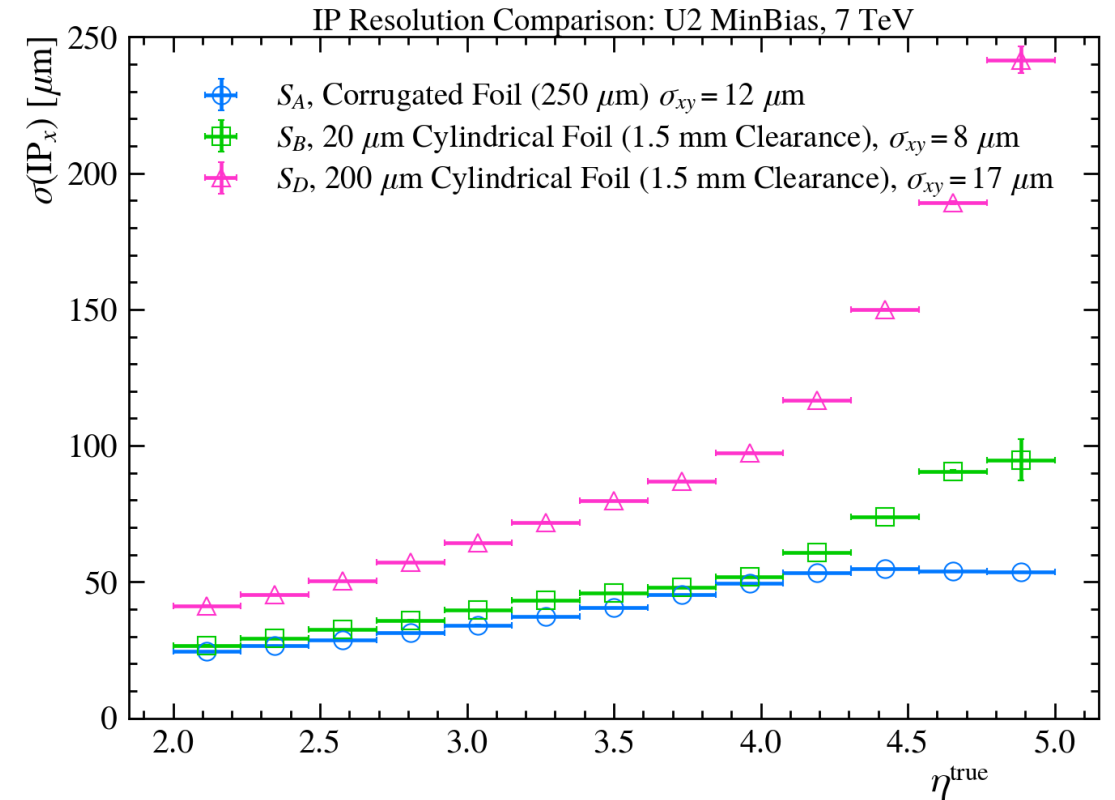
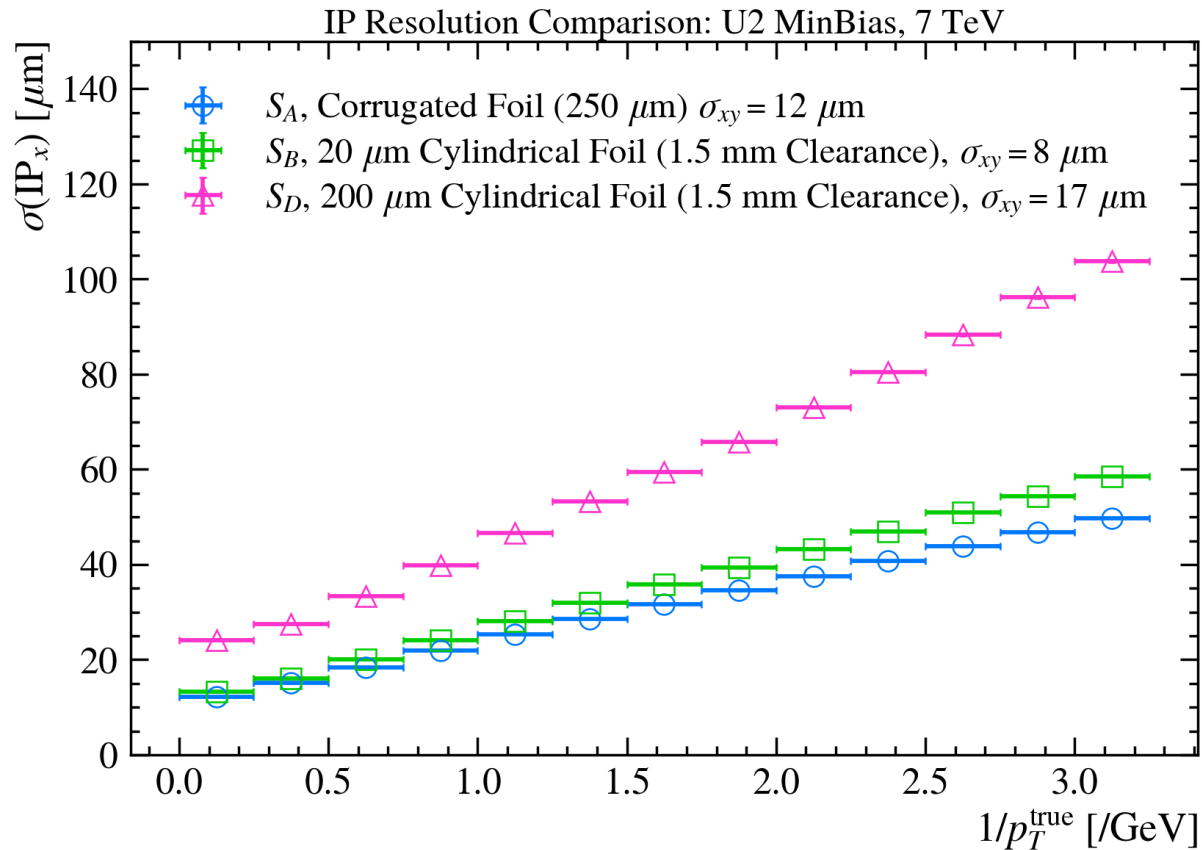
VP:ClosestPixel



# IP Resolution

- Scenario A & B clearly outperforming D
- Scenario B reliant on UTF (Ultra-Thin-Foil)

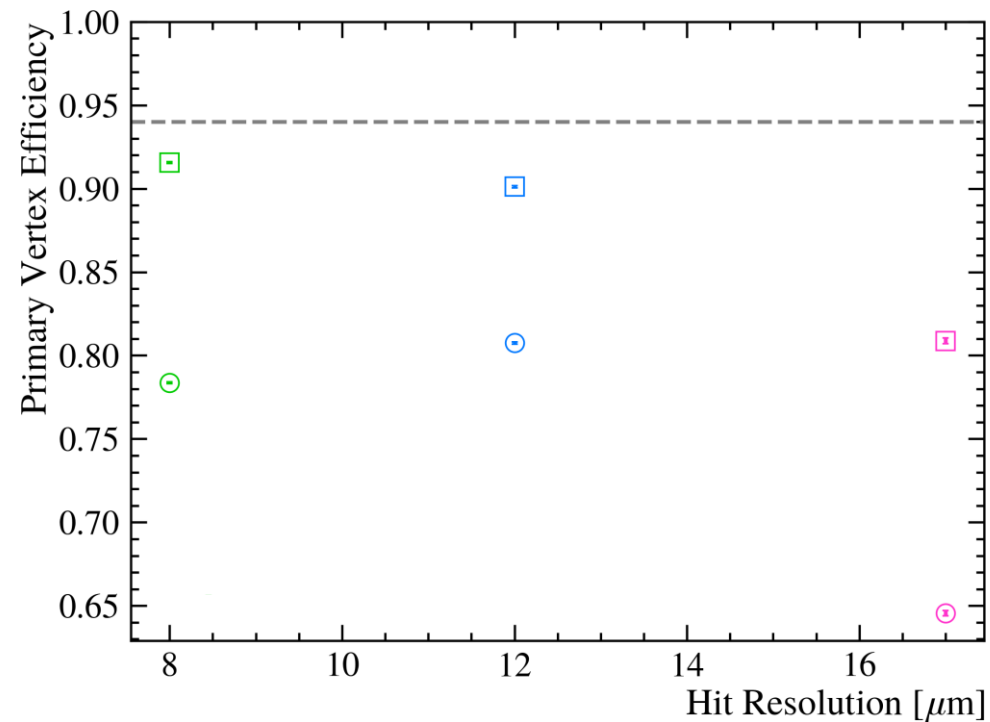
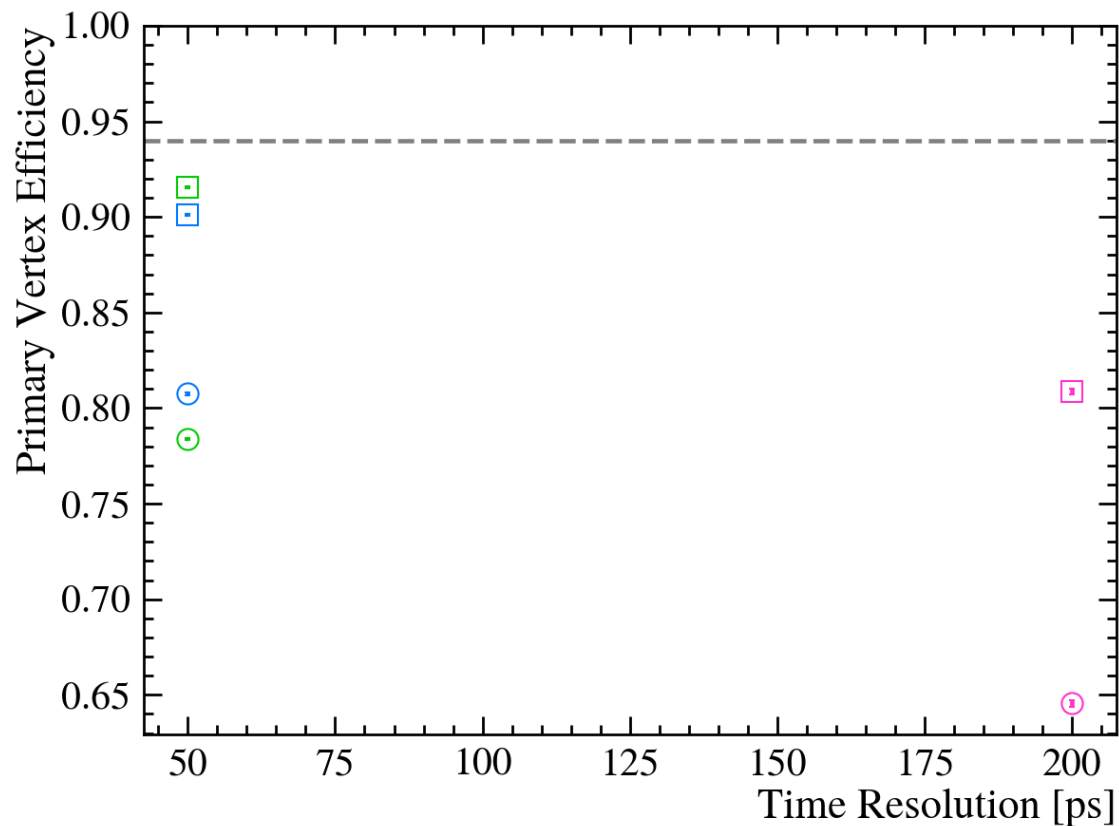
Properties ↓ Scenario →	$S_A$	$S_B$	$S_D$
Inner Radius (Closest pixel)	5.1 mm	12.5 mm	11.5 mm
Pixel Pitch (Hit Resolution)	55 (12) $\mu\text{m}$	40 (8) $\mu\text{m}$	60 (17) $\mu\text{m}$
Timing Resolution	50 ps	50 ps	200 ps
Foil Type	Corrugated	Cylindrical	Cylindrical
Foil Thickness	250 $\mu\text{m}$	20 $\mu\text{m}$	200 $\mu\text{m}$



# Vertex Reconstruction Efficiency

Properties ↓ Scenario →	$S_A$	$S_B$	$S_D$
Inner Radius (Closest pixel)	5.1 mm	12.5 mm	11.5 mm
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- Retaining near-UI primary vertex efficiency reliant on timing, scenario D would lead to significant degradation.
- Flexible chain, Moore can be re-run with any  $(\sigma_{xy}, \sigma_t)$  to optimise Scenarios.

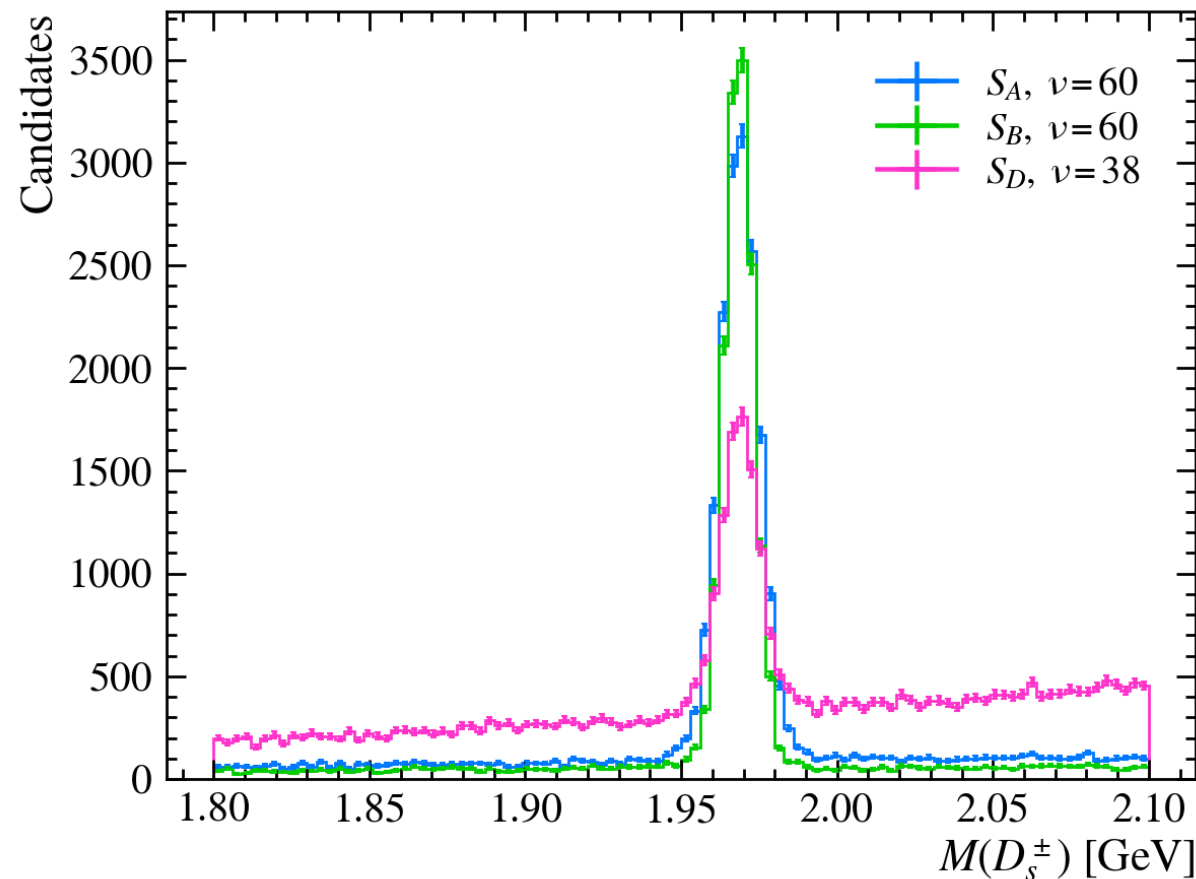
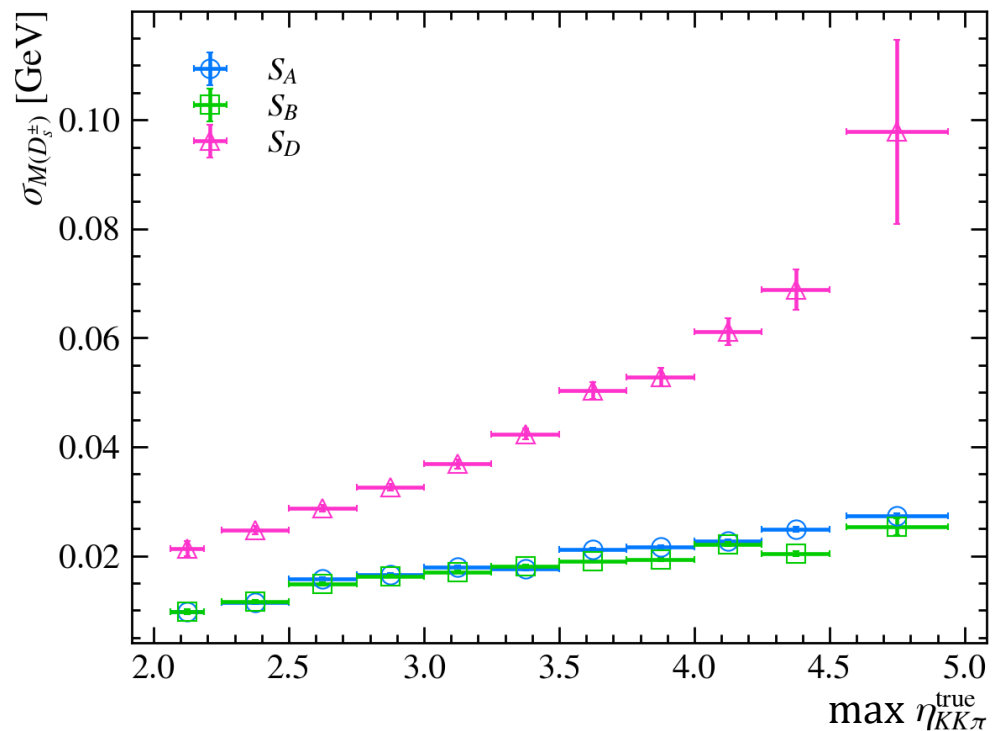


$S_A/S_B: v = 60$   
 $S_D: v = 38$

- UI,  $n_{\text{tracks}} > 25$
- $\circ$   $S_A$ , All Vertices
- $\square$   $S_A$ ,  $n_{\text{tracks}} > 25$
- $\circ$   $S_B$ , All Vertices
- $\square$   $S_B$ ,  $n_{\text{tracks}} > 25$
- $\circ$   $S_D$ , All Vertices
- $\square$   $S_D$ ,  $n_{\text{tracks}} > 25$

# $B_S^0 \rightarrow D_S^\pm (\rightarrow K^+ K^- \pi^\pm) \pi^\mp$ Reconstruction

- Event type: 13264021
- Assume perfect PID on final state particles
- **50K Events generated** ( $\nu = 60$  for  $S_A/S_B$ ,  $\nu = 38$  for  $S_D$ )
- Loose selection applied
- **“Combinatorial background” from other pile-up PVs**



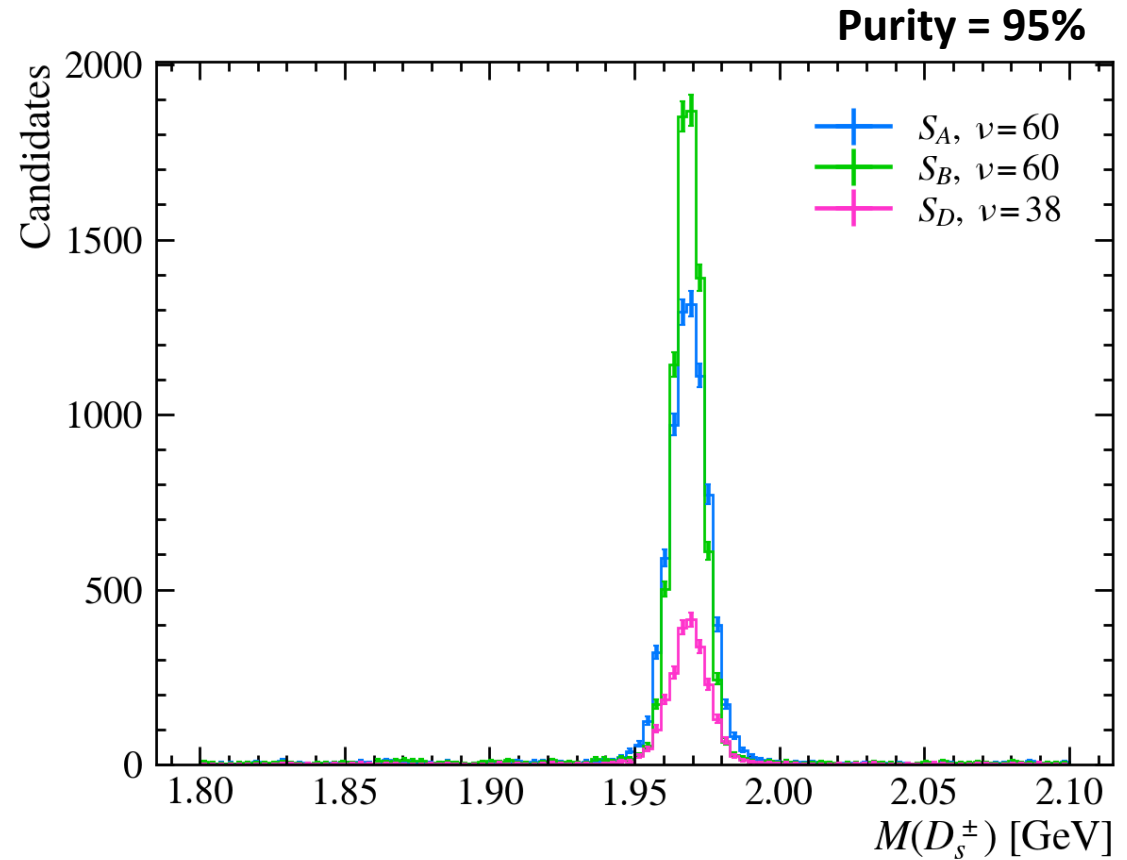
- **Smaller pitch in  $S_B$  recovers mass resolution**
- $S_D$  resolution consistently poor

# Selection Purity, $p_T^{min}$

- Fix **Sample Purity to 95%** by cutting on  $p_T^{min}$  of  $D_s^\pm$  children
- Compare  $\epsilon_{\text{Signal}} = N_{\text{Selec}}/N_{\text{Gen}}$

Results ↓ Scenario →	$S_A$	$S_B$	$S_D$
$p_T^{min}$ Cut (Purity = 95%)	796 MeV	741 MeV	1176 MeV
Signal Efficiency ( <b>Purity = 95%</b> )	<b>14.8 ± 0.2 %</b>	<b>16.2 ± 0.2 %</b>	<b>4.53 ± 0.09 %</b>
$p_T^{min}$ Cut (Purity = 90%)	576 MeV	531 MeV	891 MeV
Signal Efficiency ( <b>Purity = 90%</b> )	<b>21.1 ± 0.2 %</b>	<b>21.7 ± 0.2 %</b>	<b>7.0 ± 0.1 %</b>

- **Comparison between scenarios important**, absolute numbers less so
- Lose significantly more signal candidates with  $S_D$  to achieve same purity
- Plans to repeat this for other cut strategies ( $IP_t, IP_{\chi^2_{4D}}$ )
- **Can be evolved into a tool for a trigger rate study**



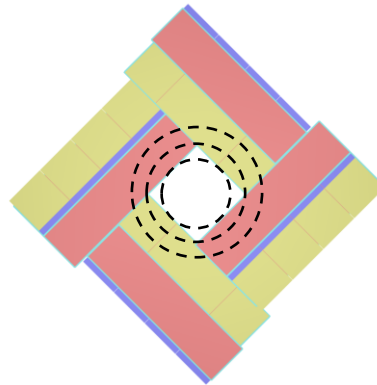
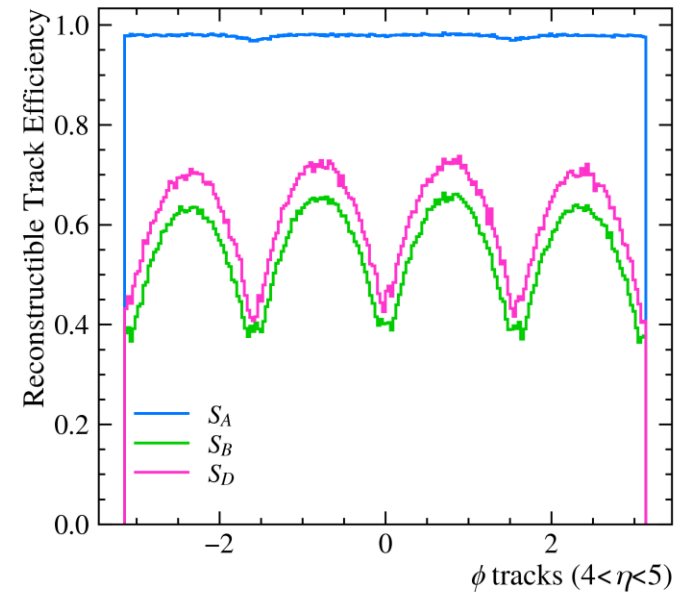
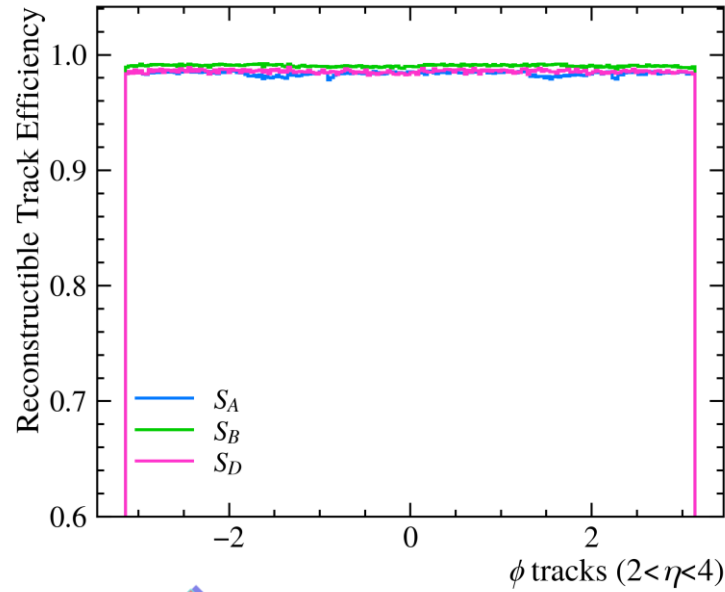
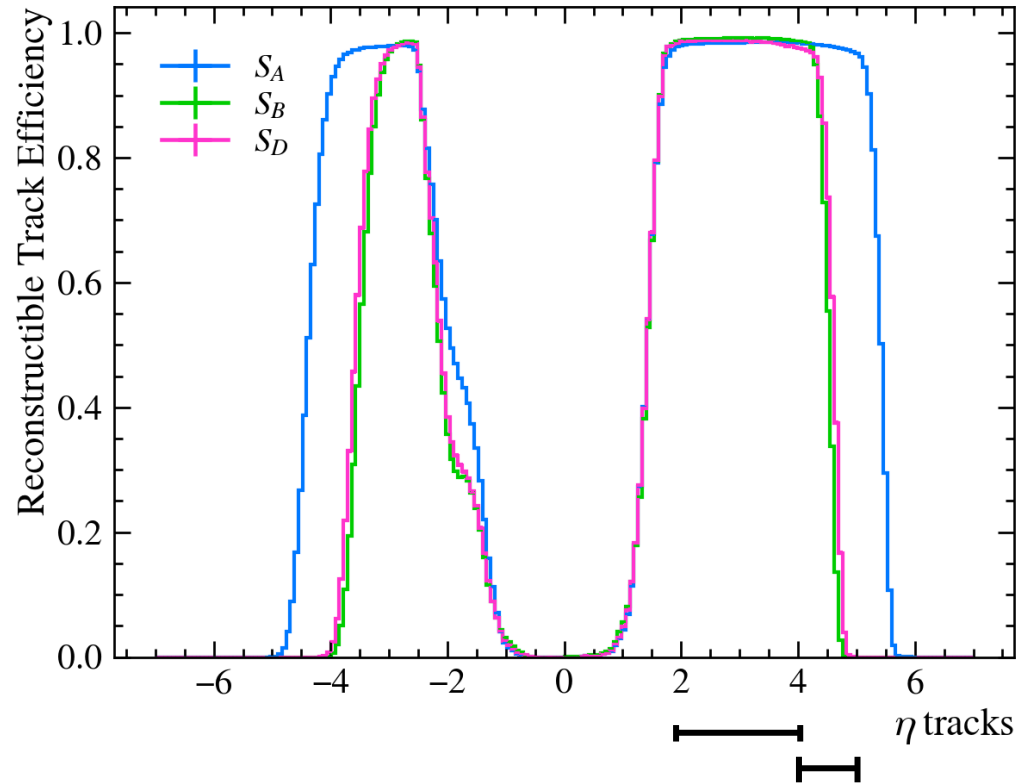
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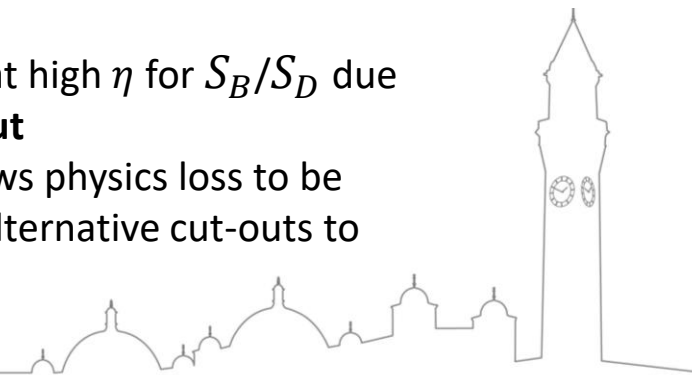
# Geometric Acceptance

Properties ↓ Scenario →	$S_A$	$S_B$	$S_D$
Inner Radius (Closest pixel)	5.1 mm	12.5 mm	11.5 mm
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- Increased radius in  $S_B$  &  $S_D$  reduces acceptance at high  $\eta$  as expected

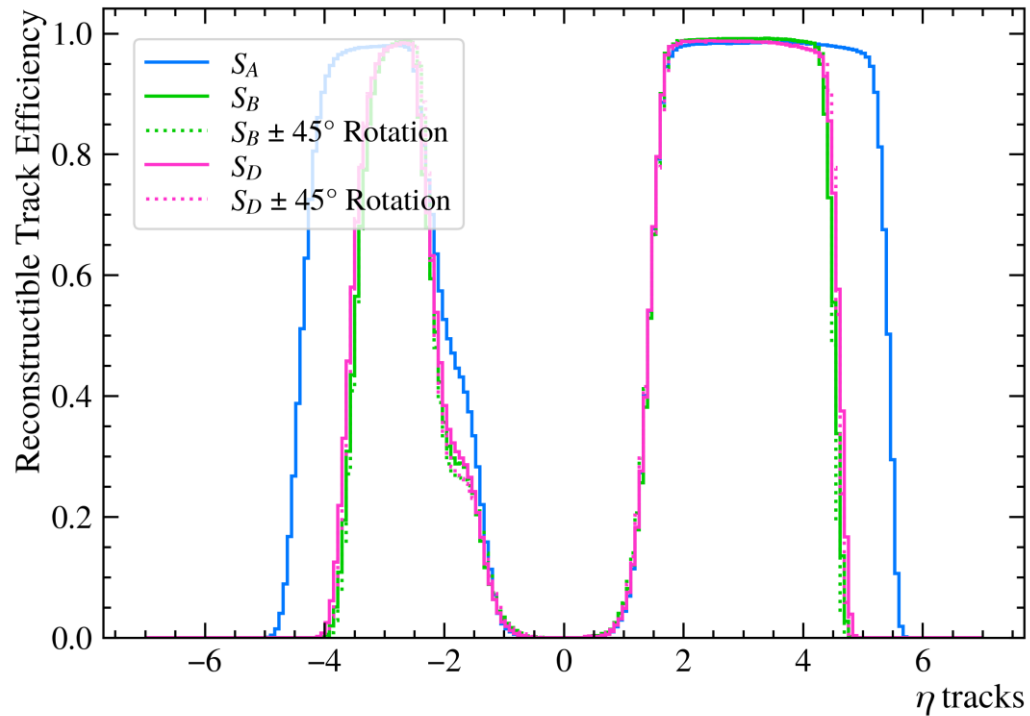


- $\phi$  dependence at high  $\eta$  for  $S_B/S_D$  due to **square cut-out**
- Framework allows physics loss to be evaluated and alternative cut-outs to be tested

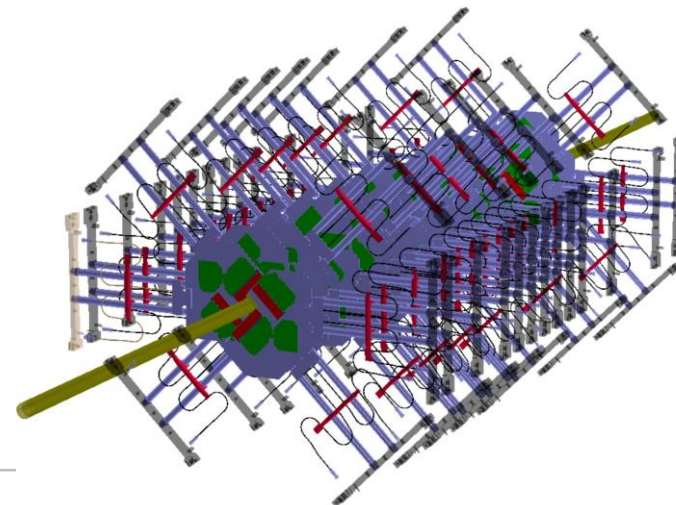
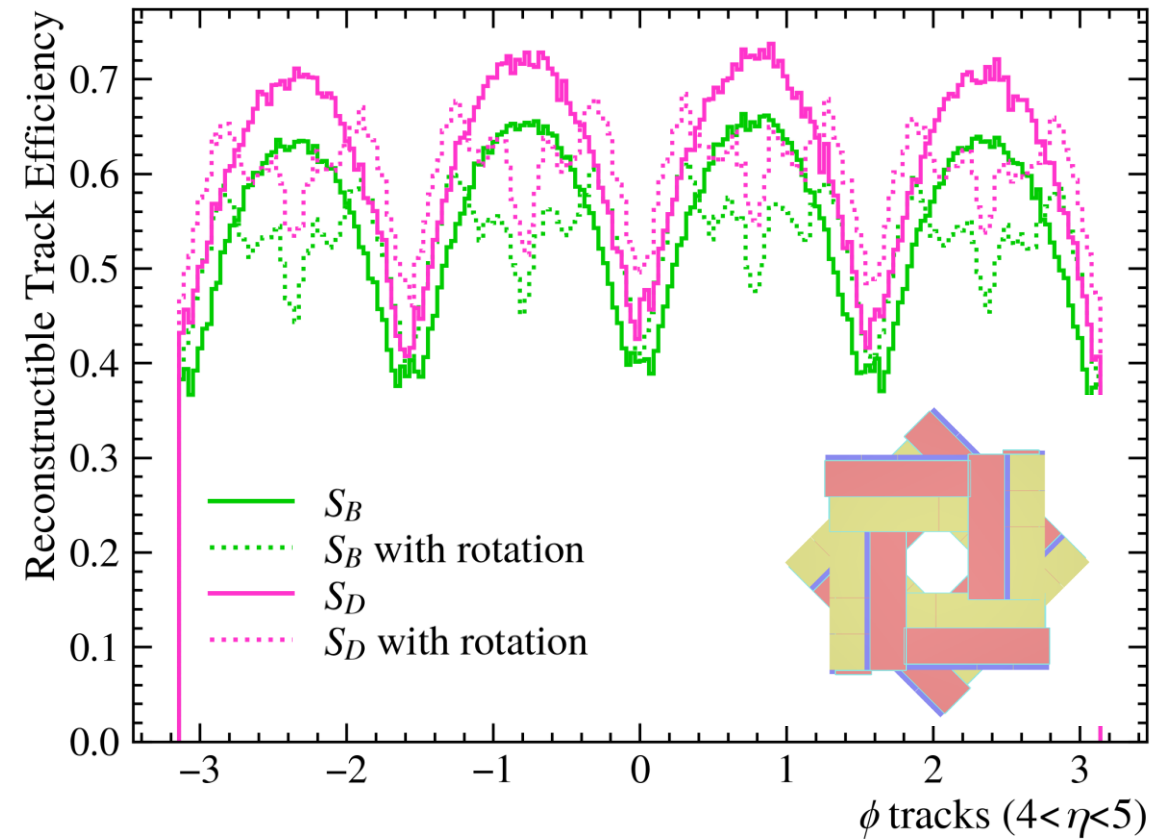


# Adding Rotation

- Expect to recover some acceptance by **rotation of modules and optimisation of z positions**
- Individual sensors rotated by altering “VP:StationNNDeltaRot”



- More detailed studies in progress, z optimisation to be implemented soon, expect to be able to recover some acceptance



## Looking Ahead : VELO

- Framework allows flexible and systematic approach to detector development
- Examples shown are changing sensor/foil configuration but material budget of ASICs and Support are major factors in performance:
  - DD4HEP and quick production of results will enable component optimisation in parallel with R&D efforts
  - New ideas can be tested and compared without significant extra work
- Plan to move forward by splitting work within VELO UII Simulation group

## Looking Ahead : Global Optimisation

- Plan to transfer the stack to a **nightly slot and run periodic tests through LHCbPR**
  - Producing an array of plots and results like shown, simplifying comparison between scenarios
- Currently running with VELO stand-alone but aiming **to involve other sub-detectors** where possible:
  - Both through full integration of prototype geometry / reconstruction algorithms
  - And through more **flexible collaboration** like VELO+CALO
  - Enables study of other key physics channels which require specific sub-detectors

